

PVDIS GEM Occupancies

Rich Holmes

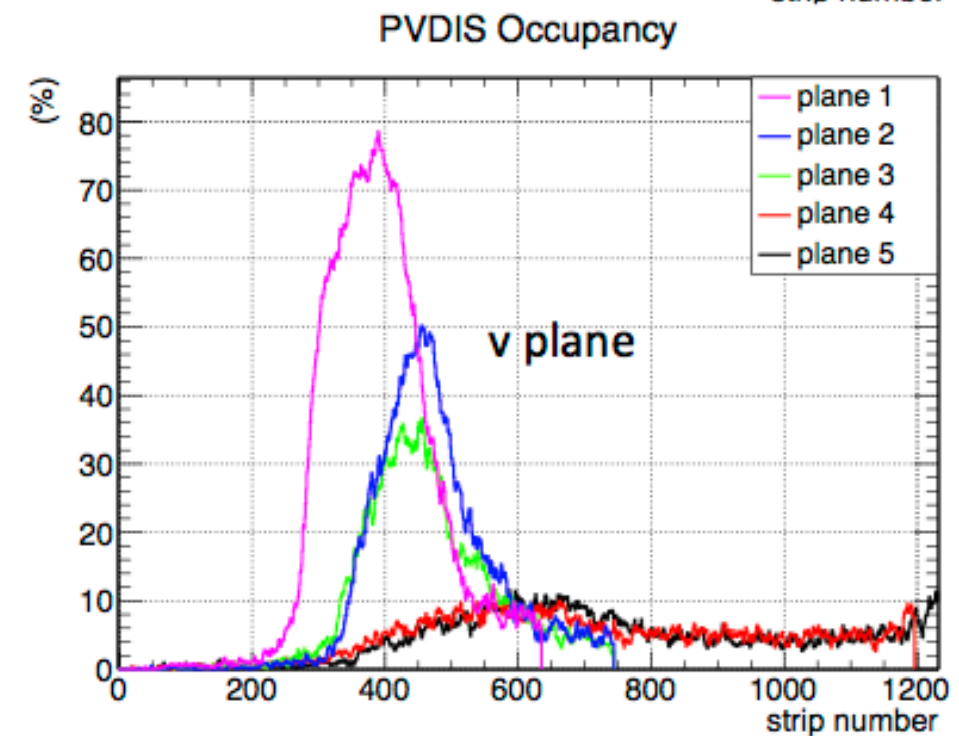
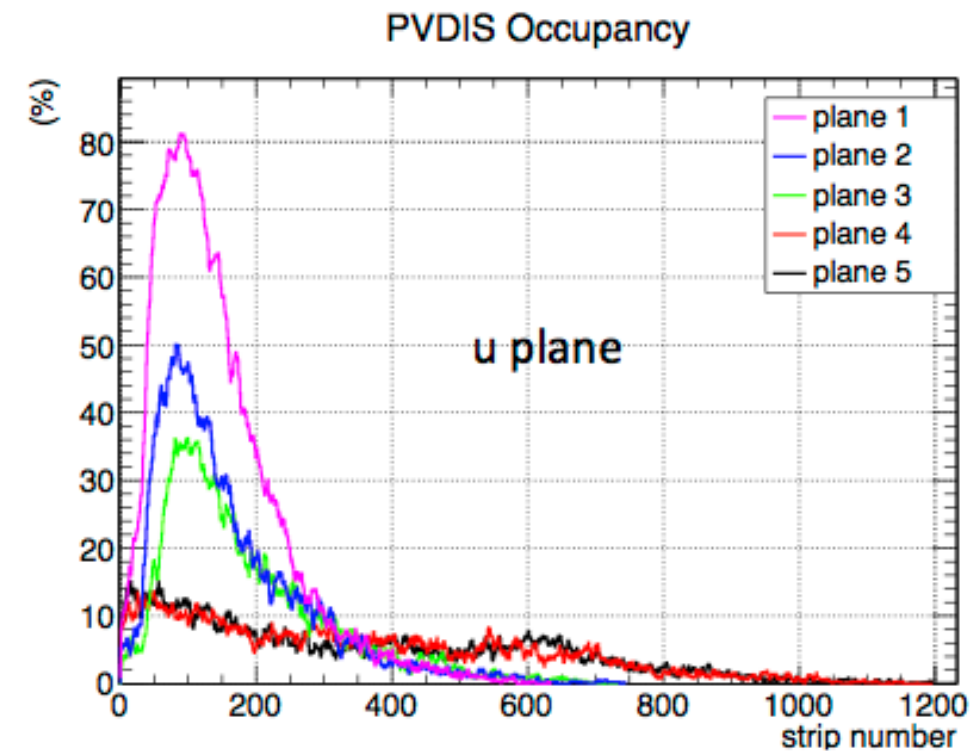
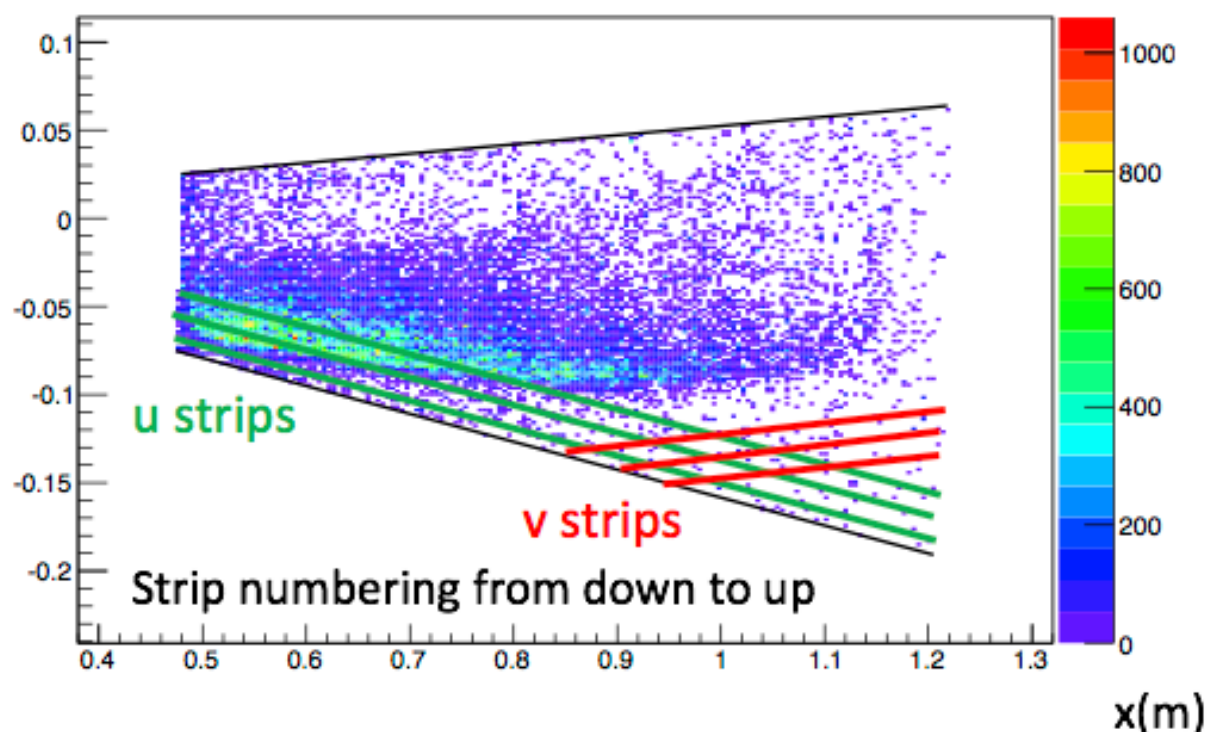
SoLID simulation meeting 9/19/2017

Weizhi's talk, March 2017 collaboration meeting

PVDIS Occupancy

- Raw Occupancy with 4 pedestal sigma cut ($\sigma = 20.7$)
- Number of strips for each readout plane:
 - 634 | 743 | 743 | 1195 | 1231
- Mean value of the raw occupancy (in %):
 - u plane: 21.9 | 11.1 | 9.2 | 4.5 | 4.4
 - v plane: 22.1 | 11.1 | 9.2 | 4.4 | 4.4
- 4 sigma cut is used in reconstruction to ensure a better efficiency

y(m) Background hit position on first tracker



GEM digitization enhancements

- Dead areas can be arbitrary polynomials
(Previously rectangles only; In addition, edges
deadened to account for GEM frames)
- Strips can be divided

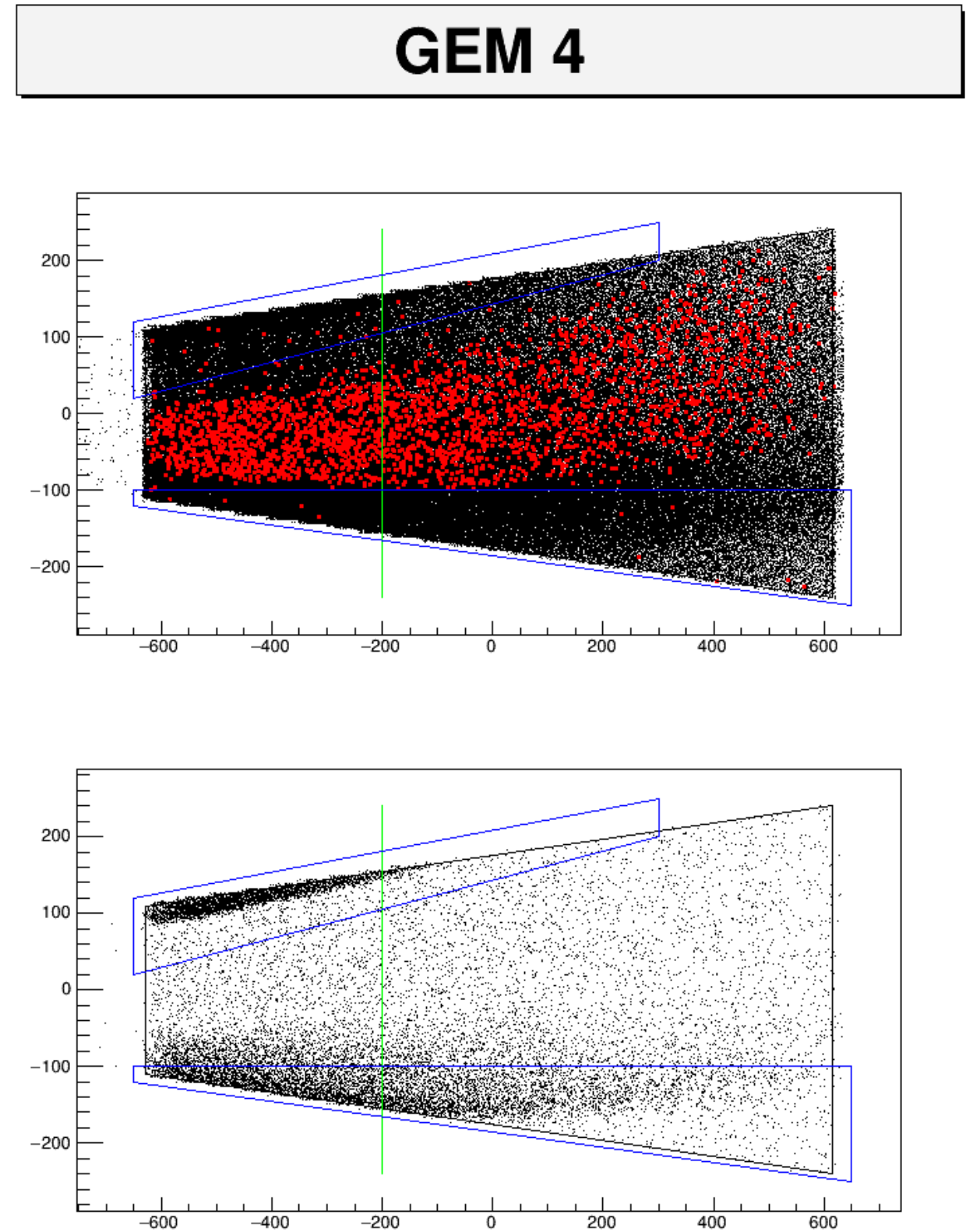
- Note a problem with previous analysis: Baffle was in its new angular position (rotated slightly in 2016 to put photon hot spots into GEM frames) but GEMs were in old positions
- This has impacts on maximum occupancies

Hit positions in GEM 4 (flux detector)

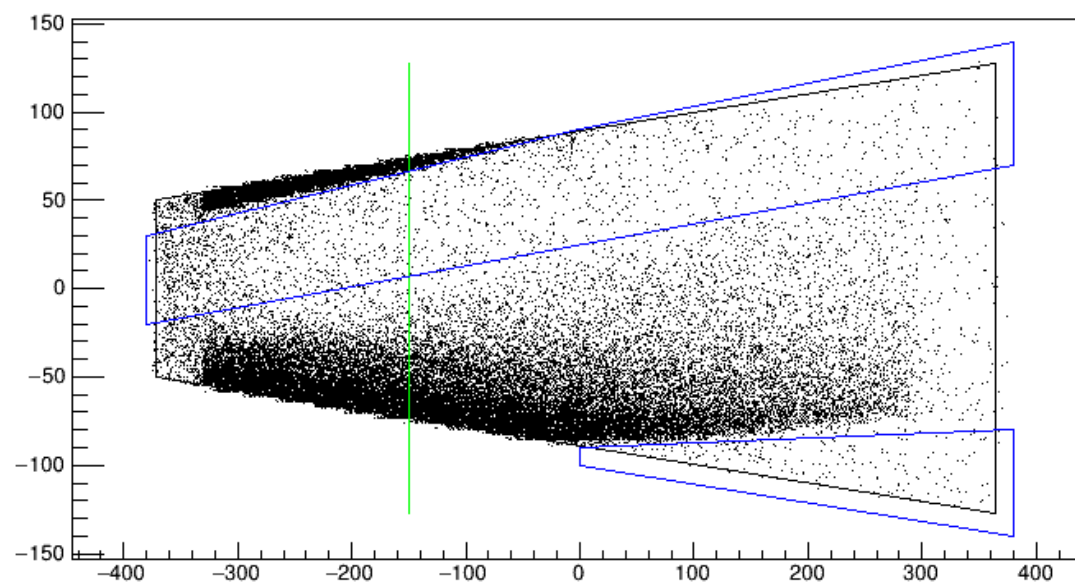
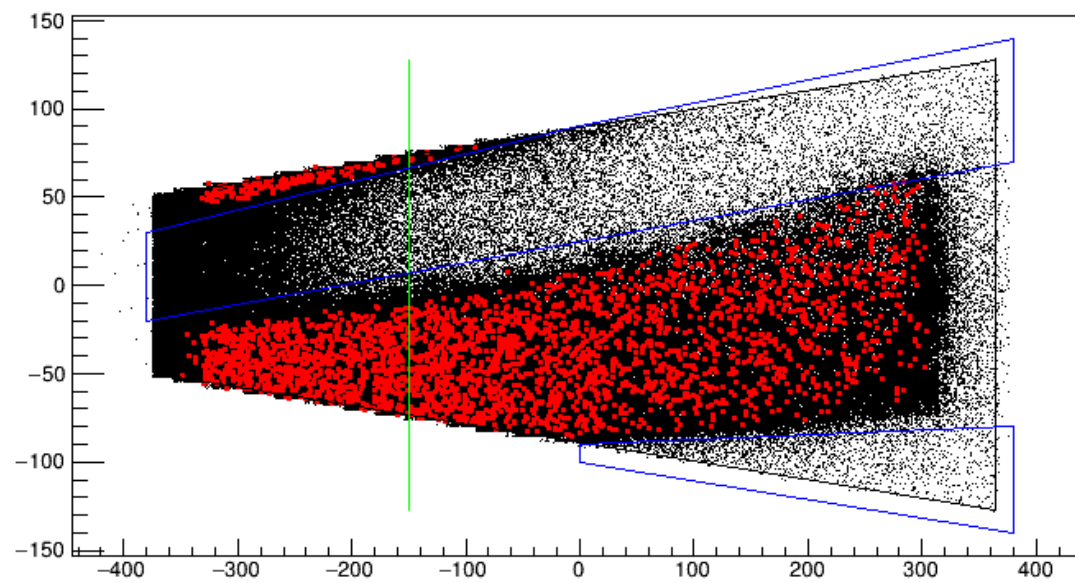
Top: Data from DIS
generator, red dots are
primary e^- with $Q^2 > 6 \text{ GeV}^2$,
 $W > 4 \text{ GeV}$, $x > 0.55$

Bottom: Data from GEANT
beam on target

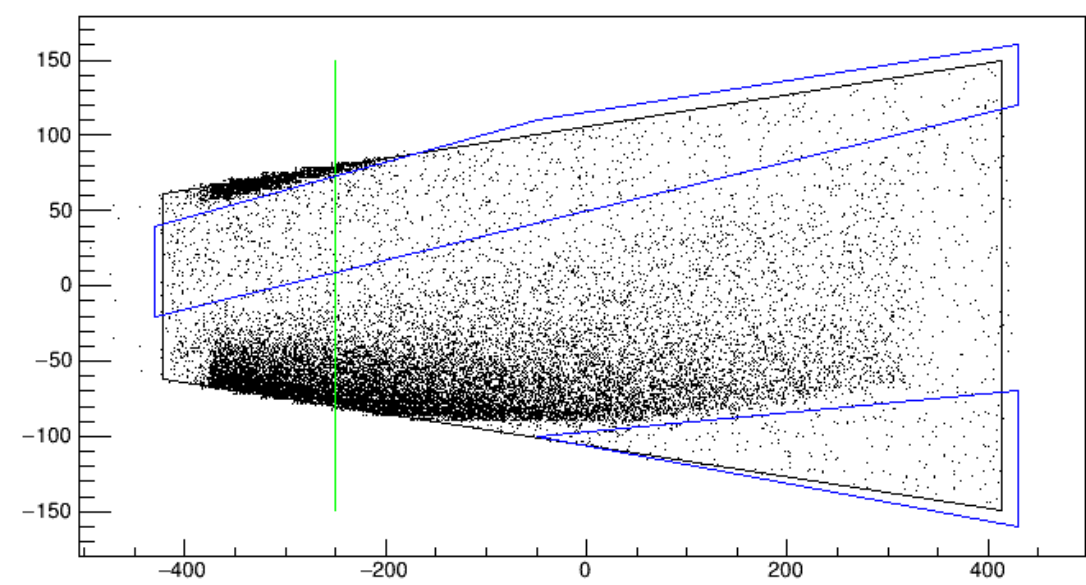
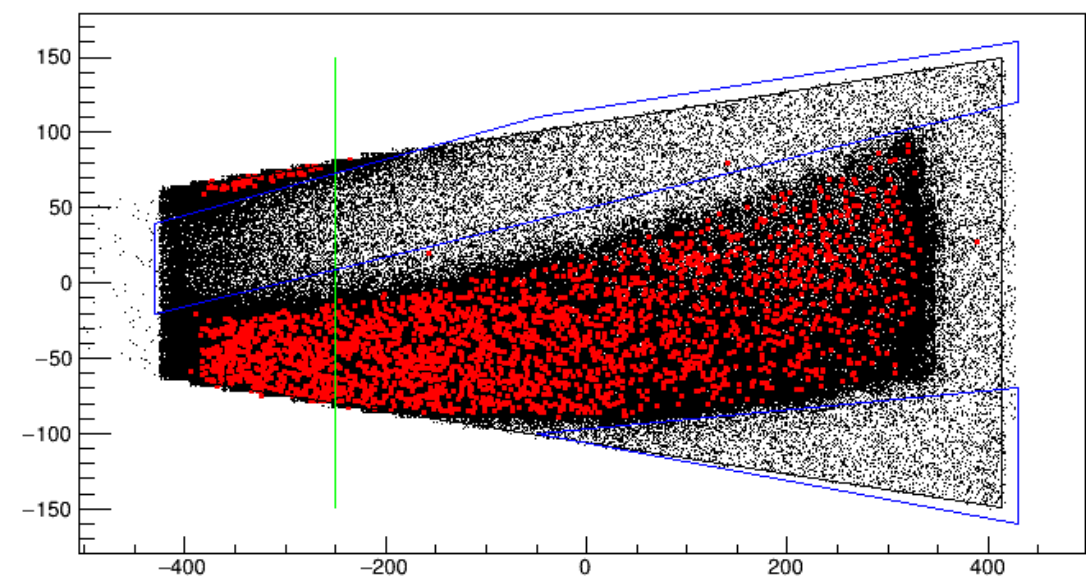
Green line: Division segment
Blue boxes: Dead regions



GEM 1

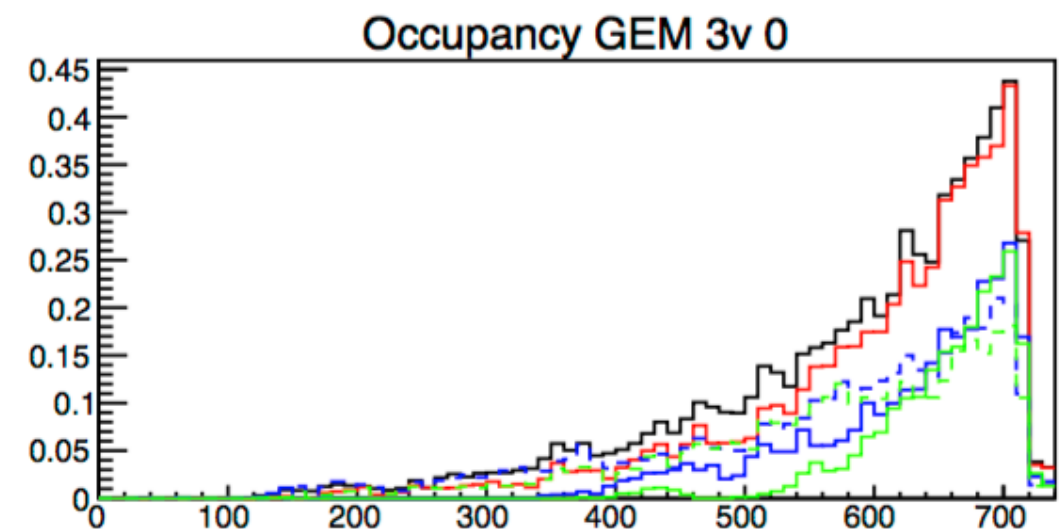
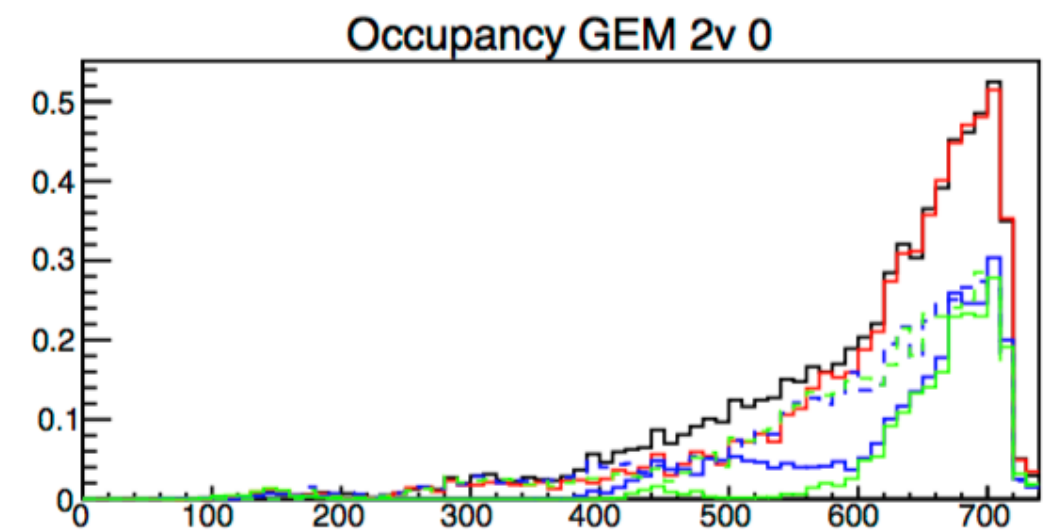
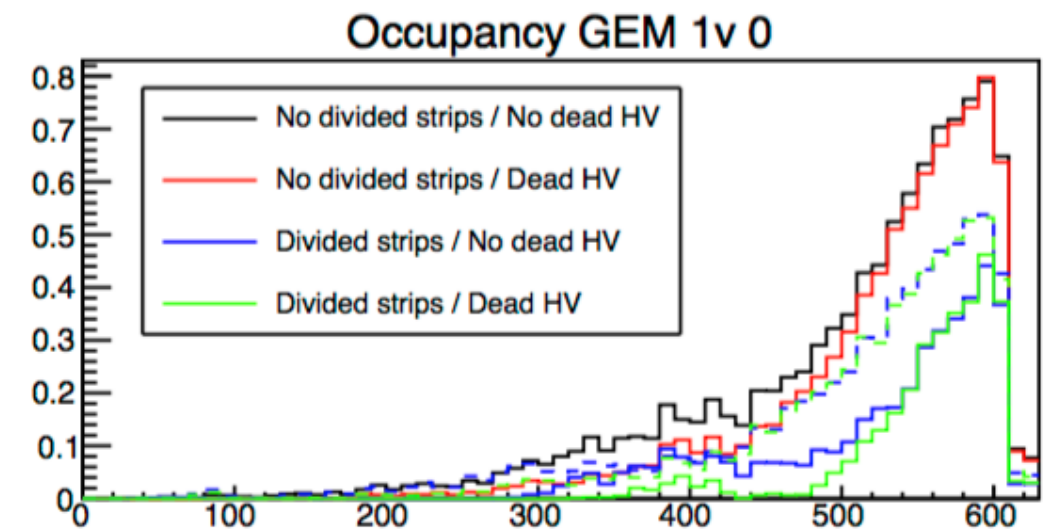


GEM 2



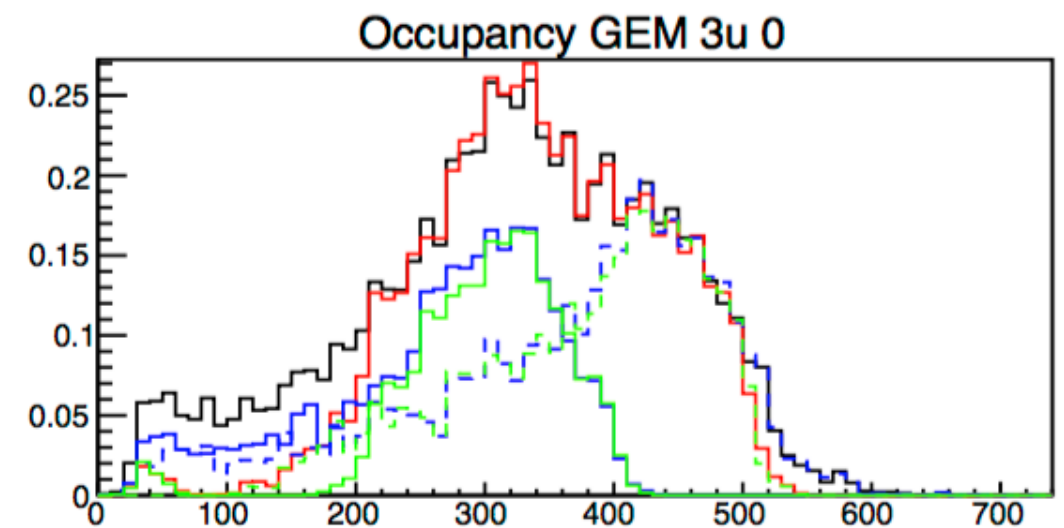
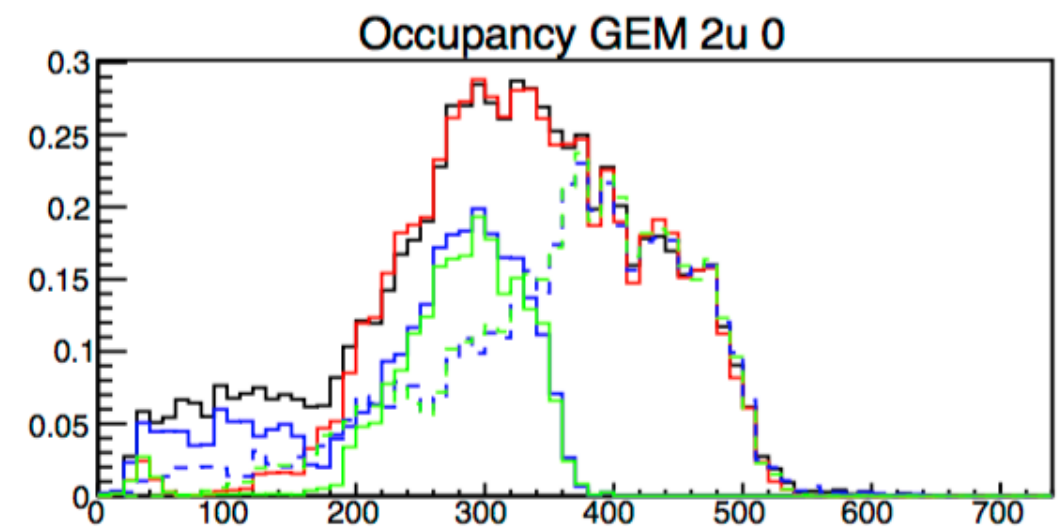
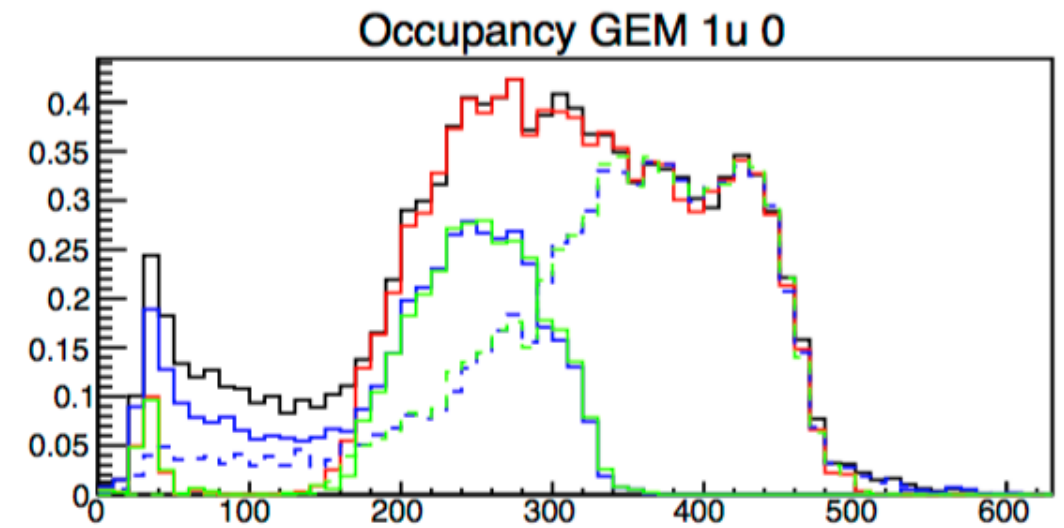
V Strips, GEMs 1–3

- 4 sigma thresholds
- GEM1 maximum occupancy
~80% with no divided strips, no
dead regions
- Dead regions have little effect on
maximum occupancies
- Reduced to ~40%–50% with
divided strips
- GEMs 2–3 maximum ~45% ->
~25%

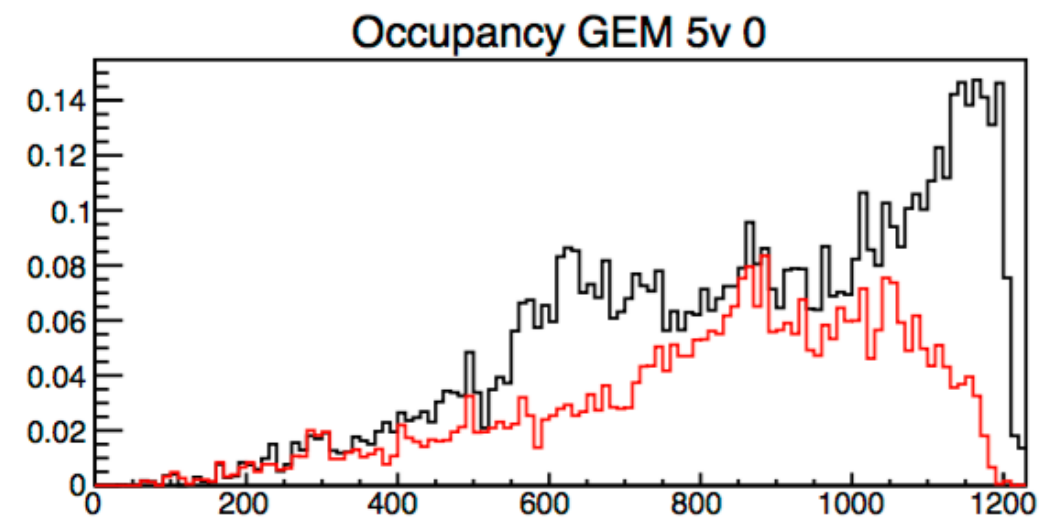
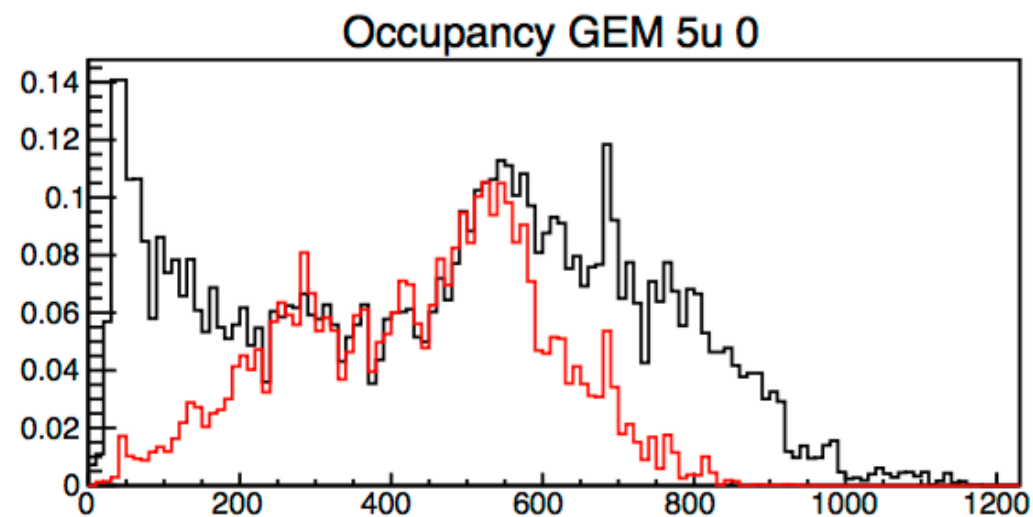
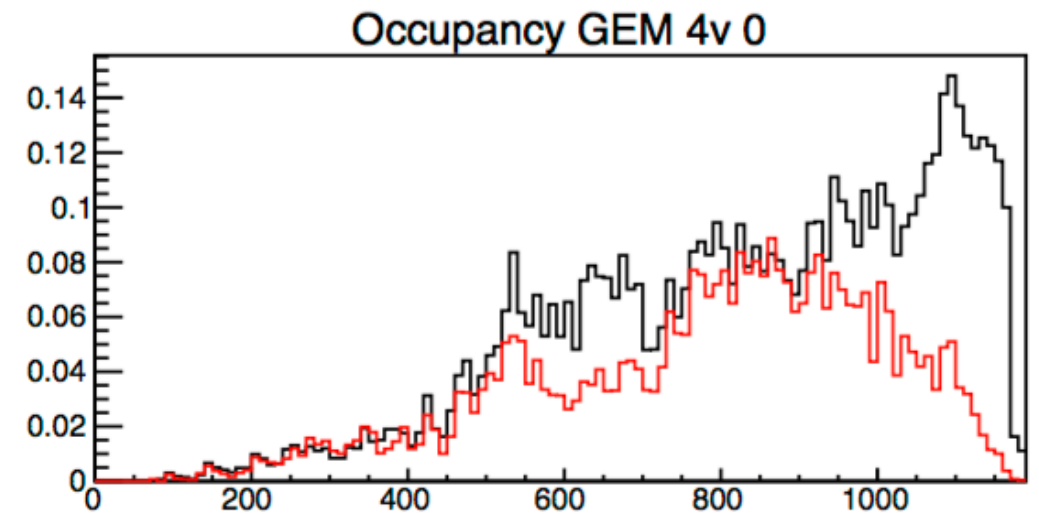
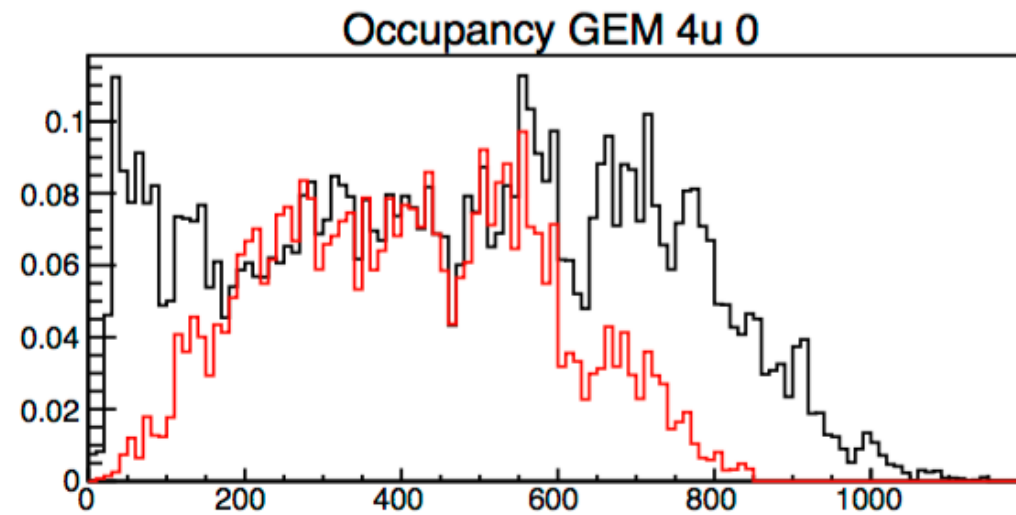


U Strips, GEMs 1–3

- GEM1 maximum $\sim 40\%$ $\rightarrow$ $\sim 30\%$
- GEMs 2–3 $\sim 25\%$ $\rightarrow$ $\sim 18\%$



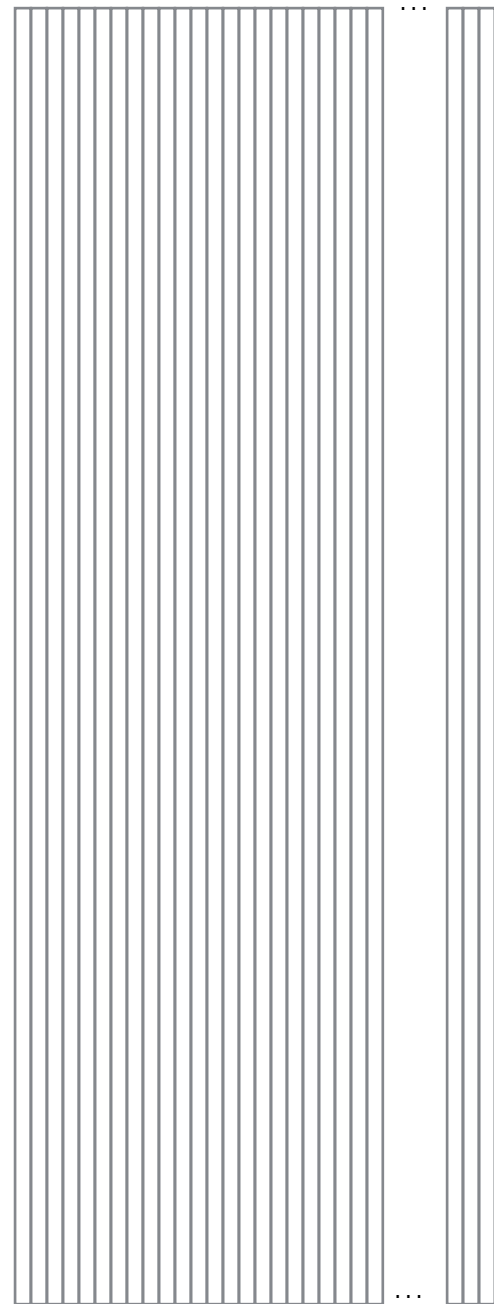
GEMs 4–5 dead regions (no divided strips)
reduce maximum, $\sim 14\% \rightarrow \sim 8\%$



- Dead areas reduce (already low) occupancies downstream.
- Divided strips reduce (high) occupancies upstream — is it enough?
- Should we revisit angular offsets? We lose some signal putting upstream photon hot spots into GEM frames. Better to keep them in live area with divided strips?
- Digitization improvements debugged and ready for tracking studies.

Extra

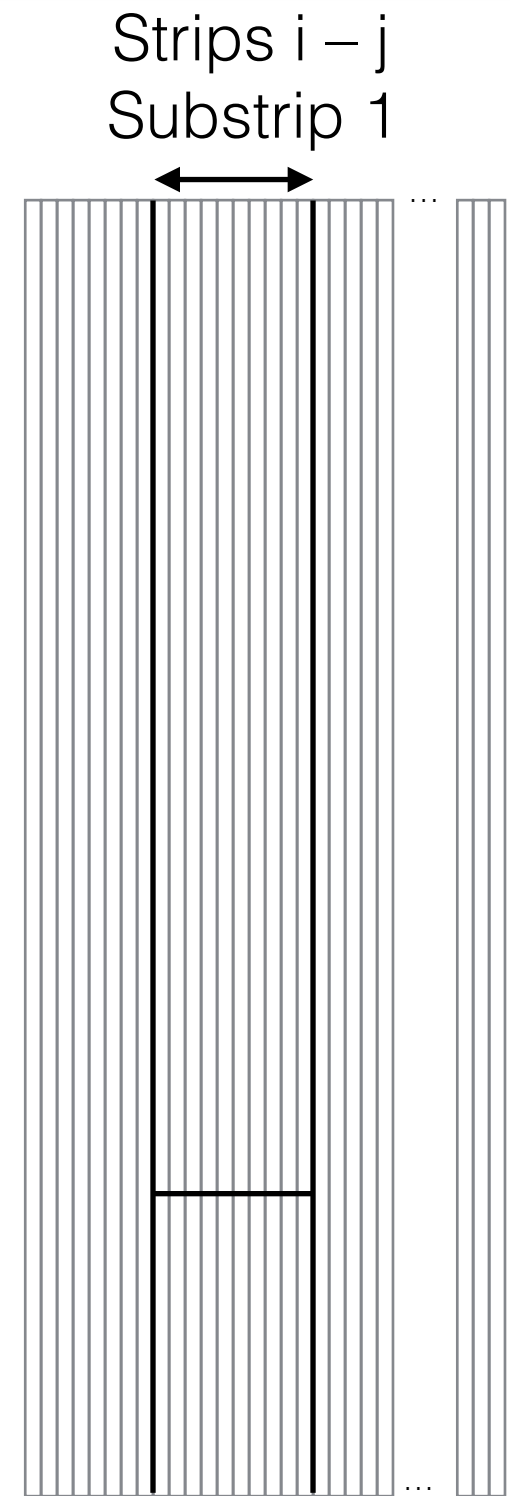
Undivided strips



◀ Strips 0 – n-1 ▶



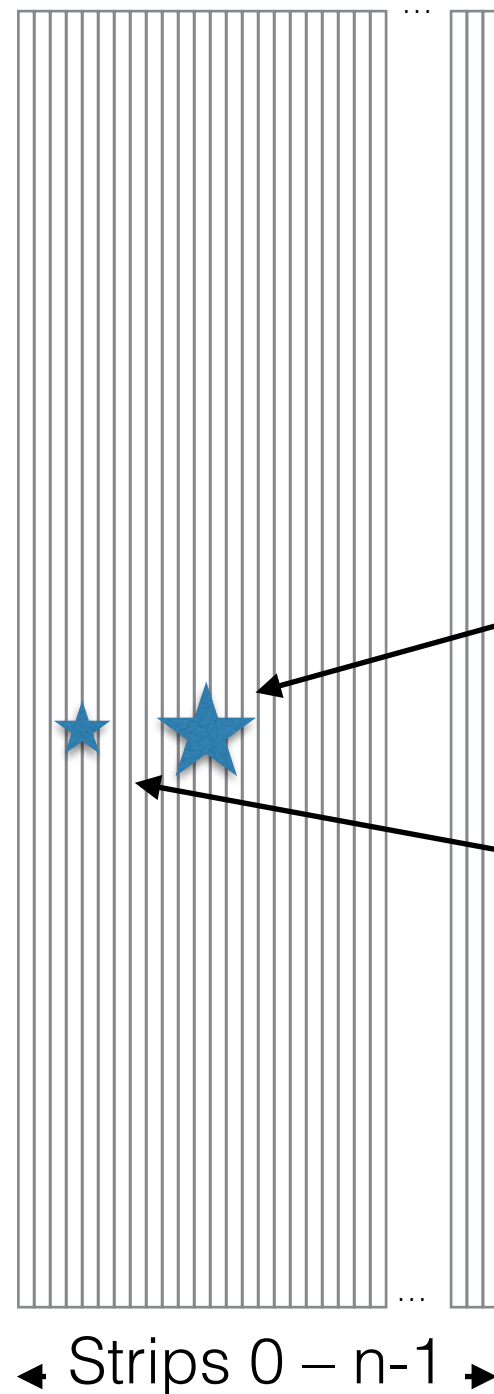
Divided strips



◀ Strips 0 – n-1 ▶

Substrip 0

Crosstalk — Undivided strips

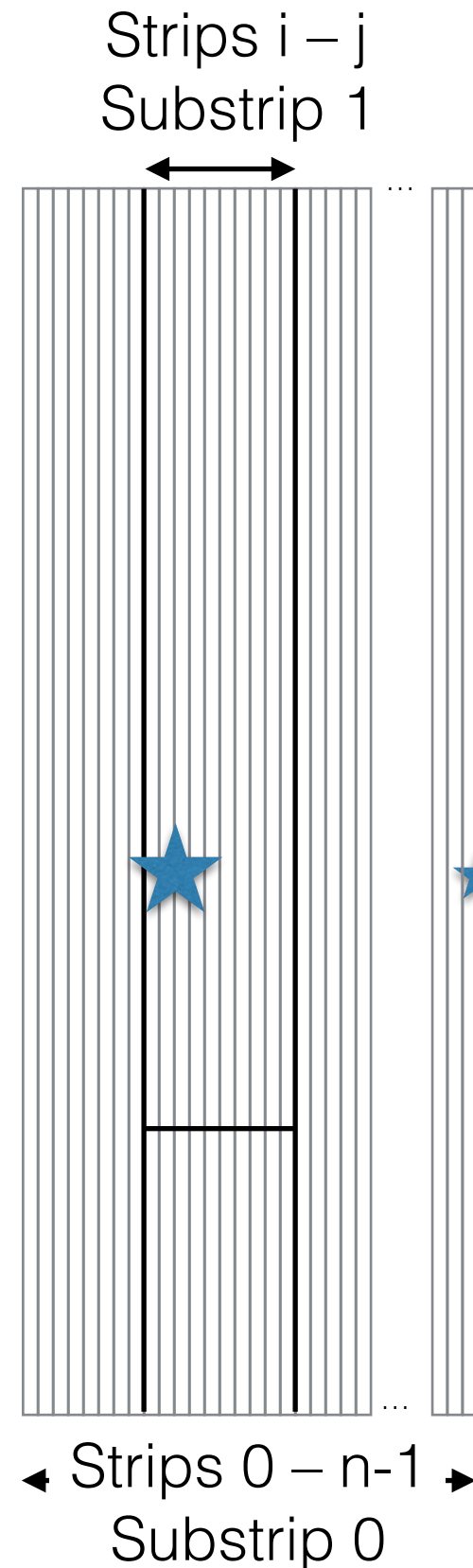


Strip	0	1	2	3	4	5	...	30	31	32	33	34	35	36	37	38	39	...	n-2	n-1
Signal	0	13	77	45	19	24	...	43	84	123	89	102	94	72	31	32	29	...	6	10

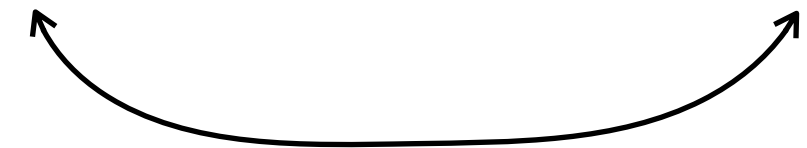
Crosstalk, any two
strips separated by 32

(Really should be only
between strips in one APV.)

Crosstalk — Divided strips



Strip	0	1	2	3	4	5	...	n-2	n-1	i	i+1	i+2	i+3	i+4	...	i+28	i+29	i+30	...	j
Substrip	0	0	0	0	0	0	...	0	0	1	1	1	1	1	...	1	1	1	...	1
Signal	0	13	77	45	19	24	...	43	84	123	89	102	94	72	...	32	29	13	...	10



Crosstalk, any two **channels** separated by 32

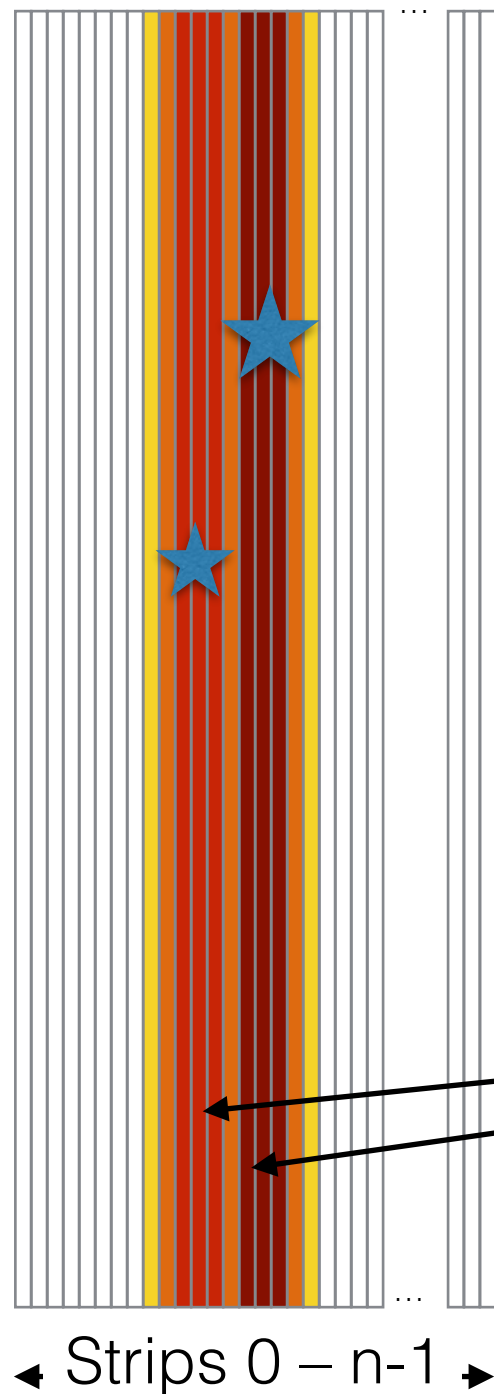
Crosstalk far from true hit

(An arrangement that interleaves substrips 0 and 1 would be easy to code and give less goofy results, but still not entirely realistic.)

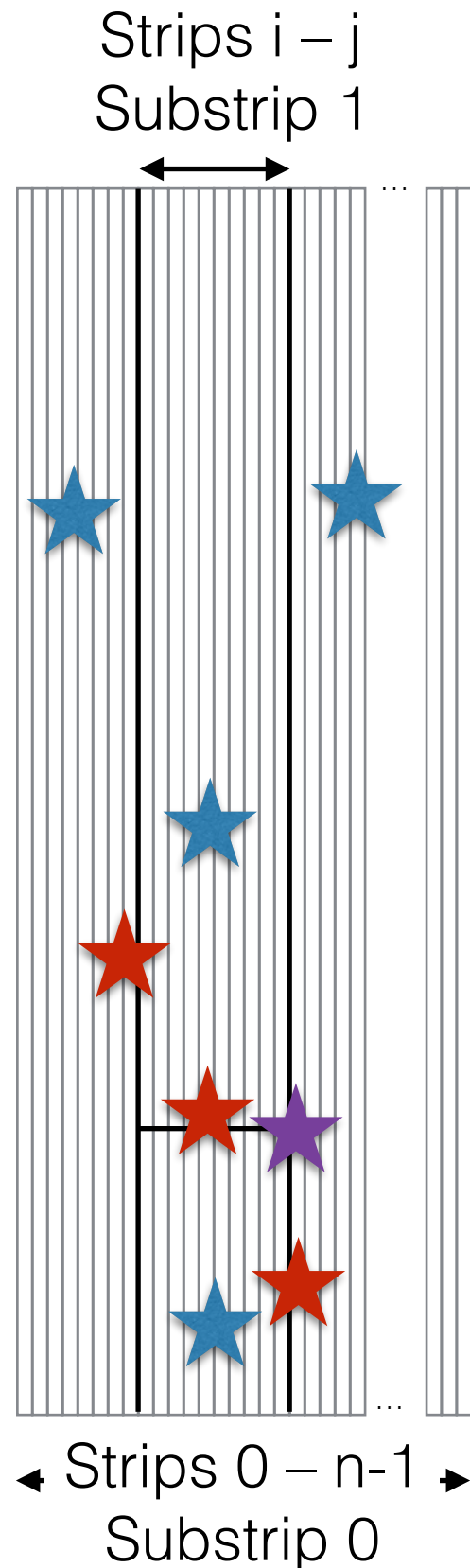
Clustering/Matching — Undivided strips

(done in tracking package, not digitization)

Strips around a local maximum are mapped to a coordinate in a single dimension. Matched based on strip crossings with other plane to generate hit coordinates in two dimensions.



Clustering/Matching — Divided strips



Must develop clusters from non-homogeneous substrip groups

- ★ Cluster in homogeneous substrip group
- ★ Cluster in two substrip groups
- ★ Cluster in three substrip groups

Partial 2-dimensional information to be matched with partial 2-dimensional information from other plane

Non trivial changes to matching and clustering algorithms